



# UTKAL INSTITUTE OF ENGINEERING & TECHNOLOGY

DISCIPLINE: ALL BRANCH	SEMESTER: 2ND SEM	NAME OF THE TEACHING FACULTY: Er.SNEHASIS DAS		
SUBJECT: ENGINEERING MECHANICS	No of Days/Per week class allotted: 4 Class P/W(60)	Semester From Date:29/01/2024		
		To Date:14/05/2024		
		No. Of Weeks: 15		
WEEK	CLASS DAY	THEORY TOPICS	REMARKS	
1 <sup>st</sup>	1 <sup>st</sup>	Fundamentals. Definitions of Mechanics, Statics	Date	Dean/Principal
	2 <sup>nd</sup>	Statics, Dynamics, Rigid Bodies		
	3 <sup>rd</sup>	Force System. Definition		
	4 <sup>th</sup>	Definition, Classification of force system according to plane & line of action		
2 <sup>nd</sup>	1 <sup>st</sup>	Characteristics of Force & effect of Force. Principles of Transmissibility & Principles of Superposition. Action & Reaction Forces & concept of Free Body Diagram		
	2 <sup>nd</sup>	Resolution of a Force. Definition		
	3 <sup>rd</sup>	Method of Resolution		
	4 <sup>th</sup>	Types of Component forces, Perpendicular components & non-perpendicular components		
3 <sup>rd</sup>	1 <sup>st</sup>	Composition of Forces. Definition, Resultant Force		
	2 <sup>nd</sup>	Method of composition of forces, such as 1.4.1 Analytical Method such as Law of Parallelogram of forces & method of resolution		
	3 <sup>rd</sup>	Graphical Method. Introduction, Space diagram, Vector diagram, Polygon law of forces.		
	4 <sup>th</sup>	Resultant of concurrent, non-concurrent & parallel force system by Analytical & Graphical Method.		
4 <sup>th</sup>	1 <sup>st</sup>	Moment of Force. Definition, Geometrical meaning of moment of a force, measurement of moment of a force & its S.I units		
	2 <sup>nd</sup>	Classification of moments according to direction of rotation, sign convention, Law of moments, Varignon's Theorem, Couple – Definition, S.I. units, measurement of couple, properties of couple		
	3 <sup>rd</sup>	EQUILIBRIUM 2.1 Definition		

	4 <sup>th</sup>	condition of equilibrium		
5 <sup>th</sup>	1 <sup>st</sup>	Analytical & Graphical conditions of equilibrium for concurrent		
	2 <sup>nd</sup>	non-concurrent & Free Body Diagram		
	3 <sup>rd</sup>	Lamia's Theorem		
	4 <sup>th</sup>	Lamia's Theorem – Statement		
6 <sup>th</sup>	1 <sup>st</sup>	Application for solving various engineering problems		
	2 <sup>nd</sup>	DOUBT CLEAR CLASS		
	3 <sup>rd</sup>	Definition of friction		
	4 <sup>th</sup>	Frictional forces		
7 <sup>th</sup>	1 <sup>st</sup>	Limiting frictional force		
	2 <sup>nd</sup>	Coefficient of Friction		
	3 <sup>rd</sup>	Angle of Friction & Repose		
	4 <sup>th</sup>	Laws of Friction		
8 <sup>th</sup>	1 <sup>st</sup>	Advantages & Disadvantages of Friction.		
	2 <sup>nd</sup>	Equilibrium of bodies on level plane		
	3 <sup>rd</sup>	Equilibrium of bodies on level plane – Force applied on horizontal & inclined plane (up & down)		
	4 <sup>th</sup>	Ladder, Wedge Friction		
9 <sup>th</sup>	1 <sup>st</sup>	CENTROID & MOMENT OF INERTIA		
	2 <sup>nd</sup>	Centroid – Definition		
	3 <sup>rd</sup>	Moment of an area about an axis		
	4 <sup>th</sup>	centroid of geometrical figures such as squares		
10 <sup>th</sup>	1 <sup>st</sup>	rectangles		
	2 <sup>nd</sup>	triangles		
	3 <sup>rd</sup>	circles		
	4 <sup>th</sup>	semicircles & quarter circles		
11 <sup>th</sup>	1 <sup>st</sup>	centroid of composite figures		
	2 <sup>nd</sup>	Moment of Inertia		
	3 <sup>rd</sup>	Moment of Inertia – Definition, Doubt Clear Class		
	4 <sup>th</sup>	Parallel axis & Perpendicular axis Theorems		
12 <sup>th</sup>	1 <sup>st</sup>	M.I. of plane lamina & different engineering sections.		
	2 <sup>nd</sup>	Assignment		
	3 <sup>rd</sup>	Definition of simple machine		
	4 <sup>th</sup>	DOUBT CLEAR CLASS		
13 <sup>th</sup>	1 <sup>st</sup>	velocity ratio of simple and compound gear train		
	2 <sup>nd</sup>	explain simple & compound lifting machine, define M.A, V.R. & Efficiency & State the relation between them		
	3 <sup>rd</sup>	State Law of Machine, Reversibility of Machine, Self Locking Machine		
	4 <sup>th</sup>	Study of simple machines – simple axle & wheel		
	1 <sup>st</sup>	single purchase crab winch & double purchase crab winch, Worm & Worm Wheel, Screw Jack.		

14 <sup>th</sup>	2 <sup>nd</sup>	Types of hoisting machine like derricks etc, Their use and working principle. No problems		
	3 <sup>rd</sup>	Kinematics & Kinetics, Principles of Dynamics		
	4 <sup>th</sup>	Newton's Laws of Motion, Motion of Particle acted upon by a constant force, Equations of motion, DeAlembert's Principle		
15 <sup>th</sup>	1 <sup>st</sup>	Work, Power, Energy & its Engineering Applications		
	2 <sup>nd</sup>	Kinetic & Potential energy & its application.		
	3 <sup>rd</sup>	Momentum & impulse		
	4 <sup>th</sup>	conservation of energy & linear momentum, collision of elastic bodies, and Coefficient of Restitution.		

*Onehosi's Das*

HOD

*Chittaranjan Parida*

DEAN

*[Signature]*

PRINCIPAL